

FISH DETECTION

LBP CASCADE CLASSIFIER

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[AQUARIUM AR]
THE **OUTLINE**

1. RESEARCH OBJECTIVES
 - a. AR for aquarium
 - b. System requirement
2. PREVIOUS RESEARCHES
3. THE PROPOSAL
4. EVALUATION
5. CONCLUSION

AQUARIUM AR

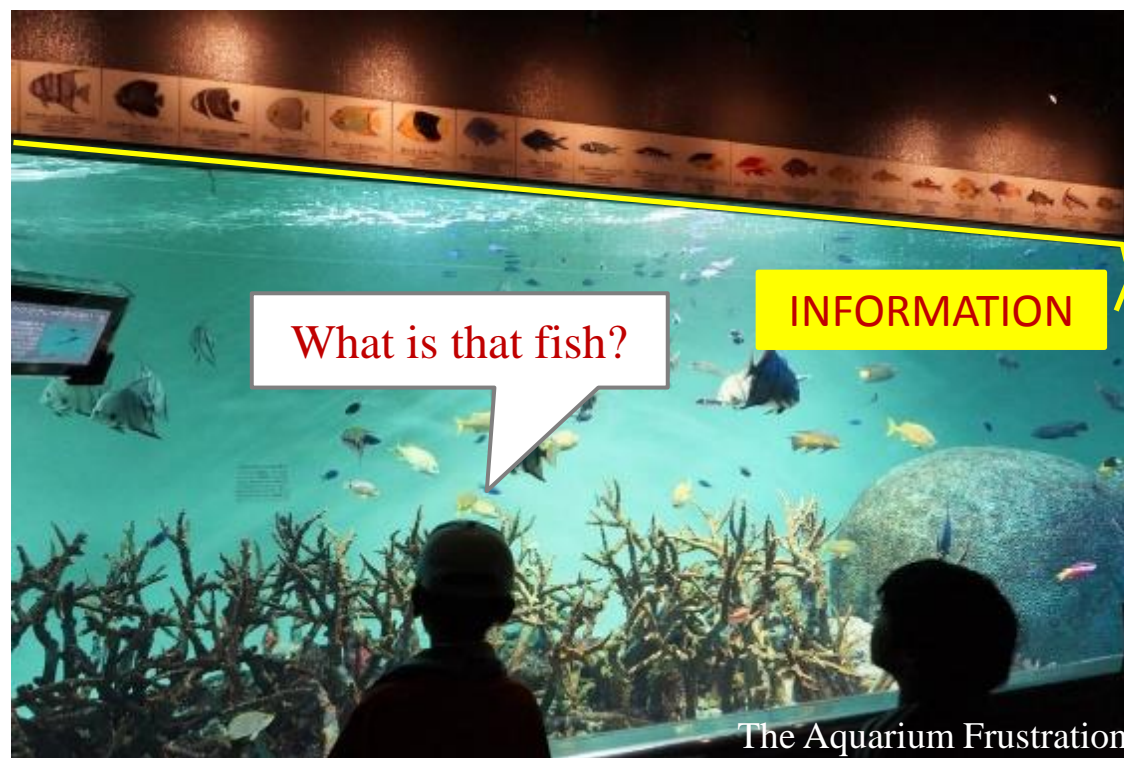
THE OBJECTIVES

AR FOR AQUARIUM

_ AR: overlaying object's information on real time video feed

_ AR for **Aquarium**

- Overlaying fish information in **real time**
- **Low** computational Cost



AQUARIUM AR

THE OBJECTIVES

AR FOR AQUARIUM

_ AR: overlaying object's information on real time video feed

_ AR for **Aquarium**

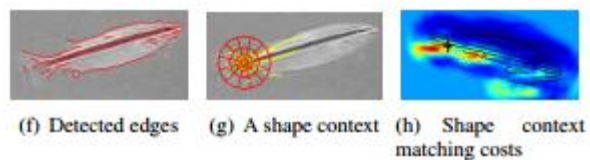
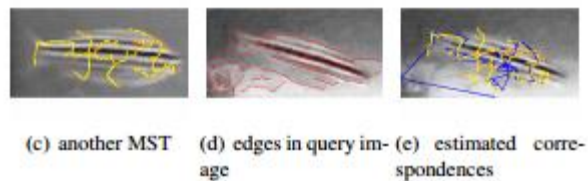
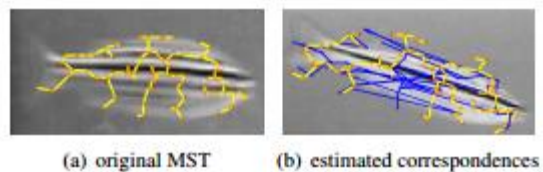
- Overlaying fish information in **real time**
- **Low** computational Cost
- Simple **sample** collection



AQUARIUM AR RESEARCH

PREVIOUS RESEARCHES

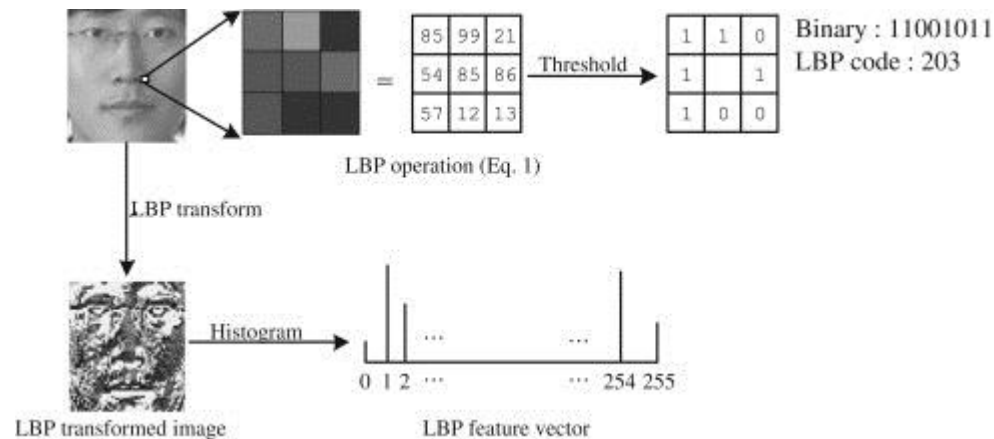
- _ Fish **discrimination**
- _ Based on **complex** texture features of the fish
- _ Operate under relatively **ideal** environment
- _ Computational **costly**



AQUARIUM AR RESEARCH

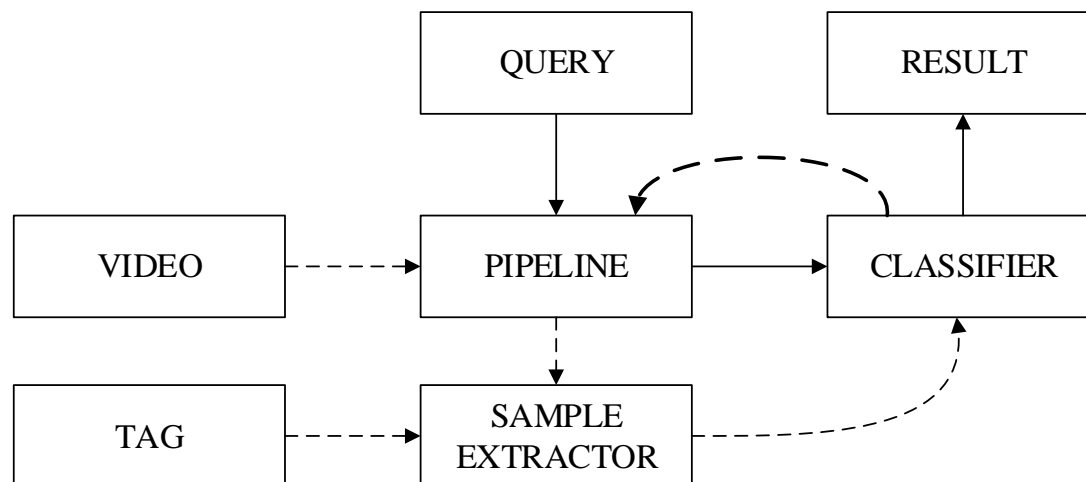
THIS RESEARCH

- _ Fish **detection** and **discrimination**
- _ Based on **simple** LBP features
- _ Image **processing** pipeline to **enhance** detection performance
- _ Operate under less **ideal** environment
- _ **Low** computational demand



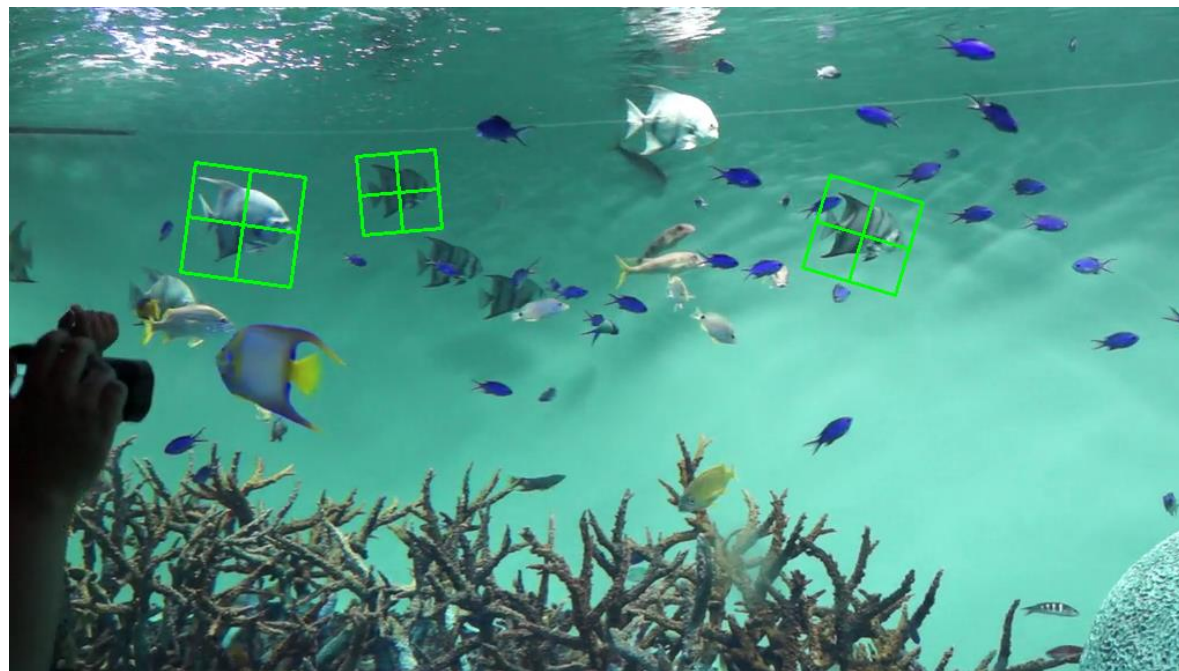
AQUARIUM AR RESEARCH

FRAMEWORK OF PROPOSED SYSTEM

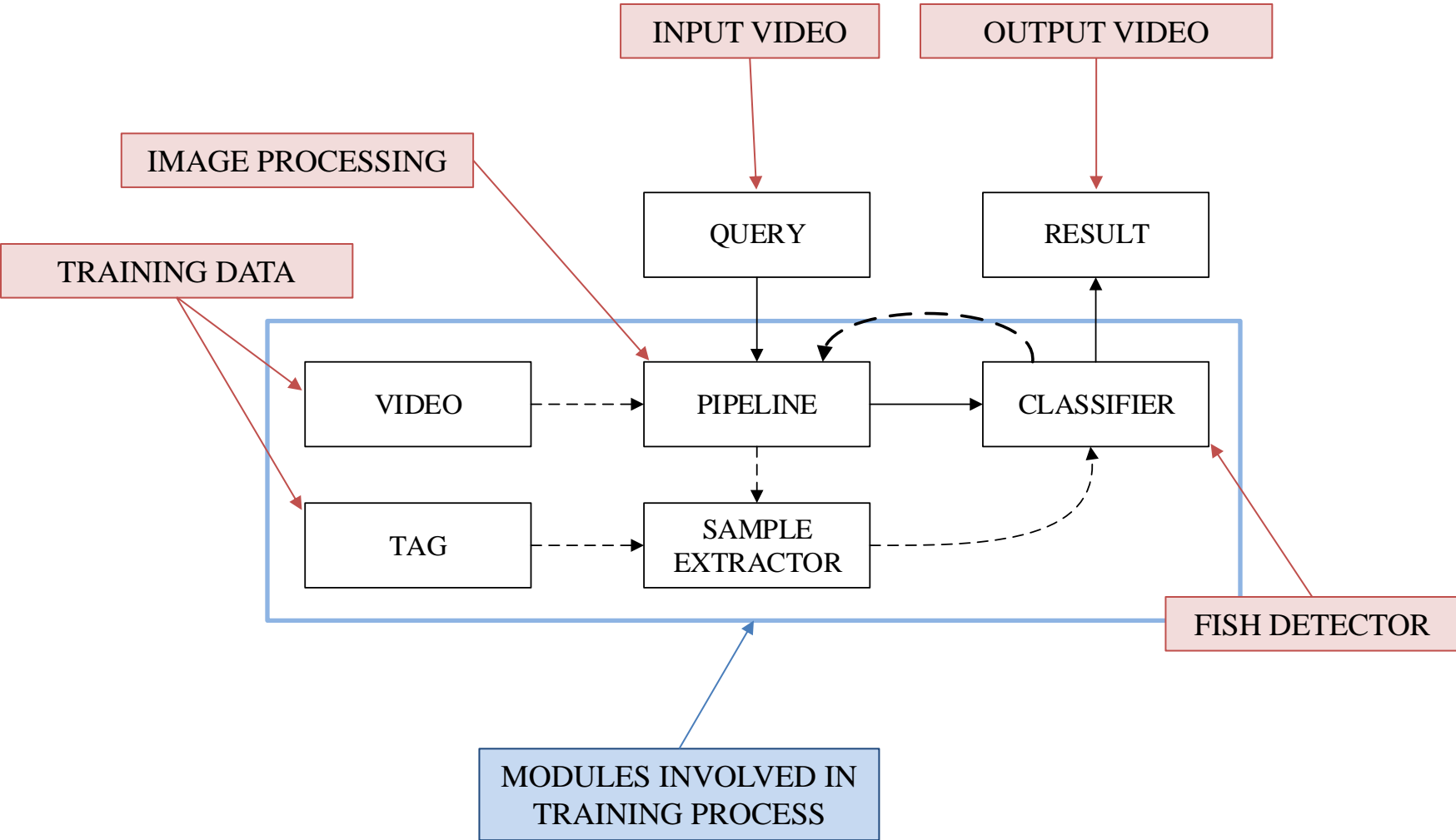


AQUARIUM AR RESEARCH

SAMPLES COLLECTION



- _ **Manually** tagging process
- _ **Custom** software developed for tagging
- _ Around **400** tags an hour
- _ No special installment required



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THE PROJECT

THE PIPELINE

- _ **Highlight** dominate color of the fish
- _ More or less a **fundamental** form of background removal
- _ **Inconsistent** output, but a strong complement to cascade classifier

$$P(h) = \iint P(h, l, s) dl ds$$

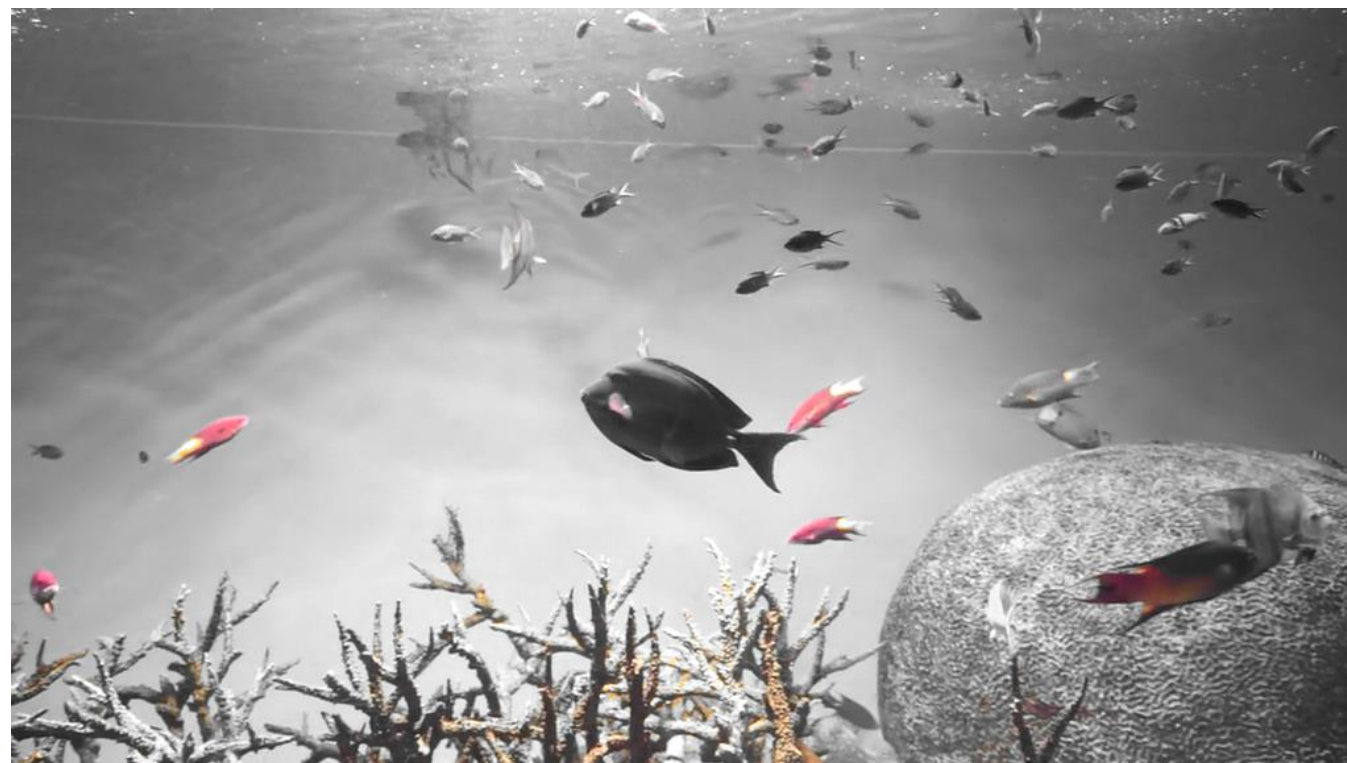
$$P(h) = P_p(h) - P_n(h)$$

$$H(h) = T(P(h), 0) = \begin{cases} P(h) & \text{if } P(h) > 0 \\ 0 & \text{if } P(h) \leq 0 \end{cases}$$

$$H(h) = \frac{H(h) - \min(H(h))}{\max(H(h)) - \min(H(h))}$$

$$O(x, y) = H(I_h(x, y))$$

[AQUARIUM AR
THE EXPERIMENT]



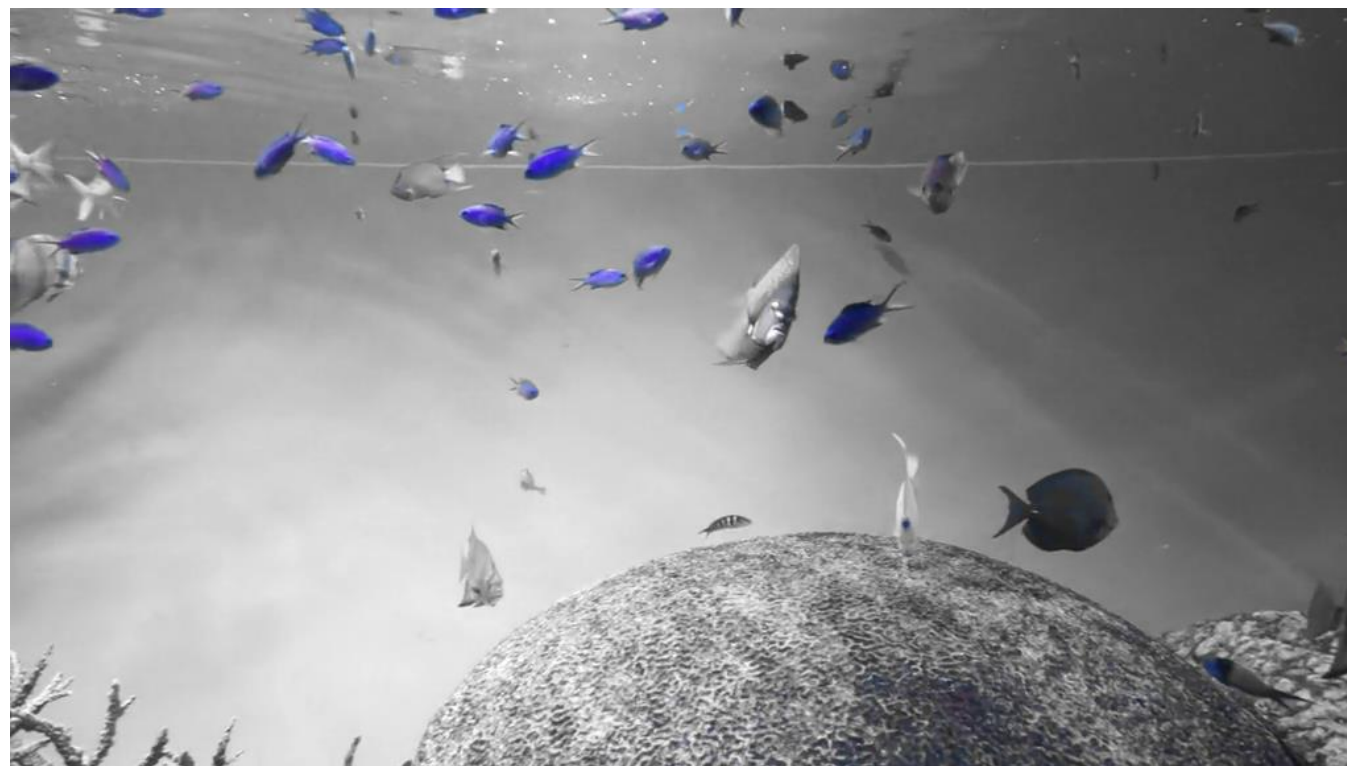
[AQUARIUM AR
THE EXPERIMENT]



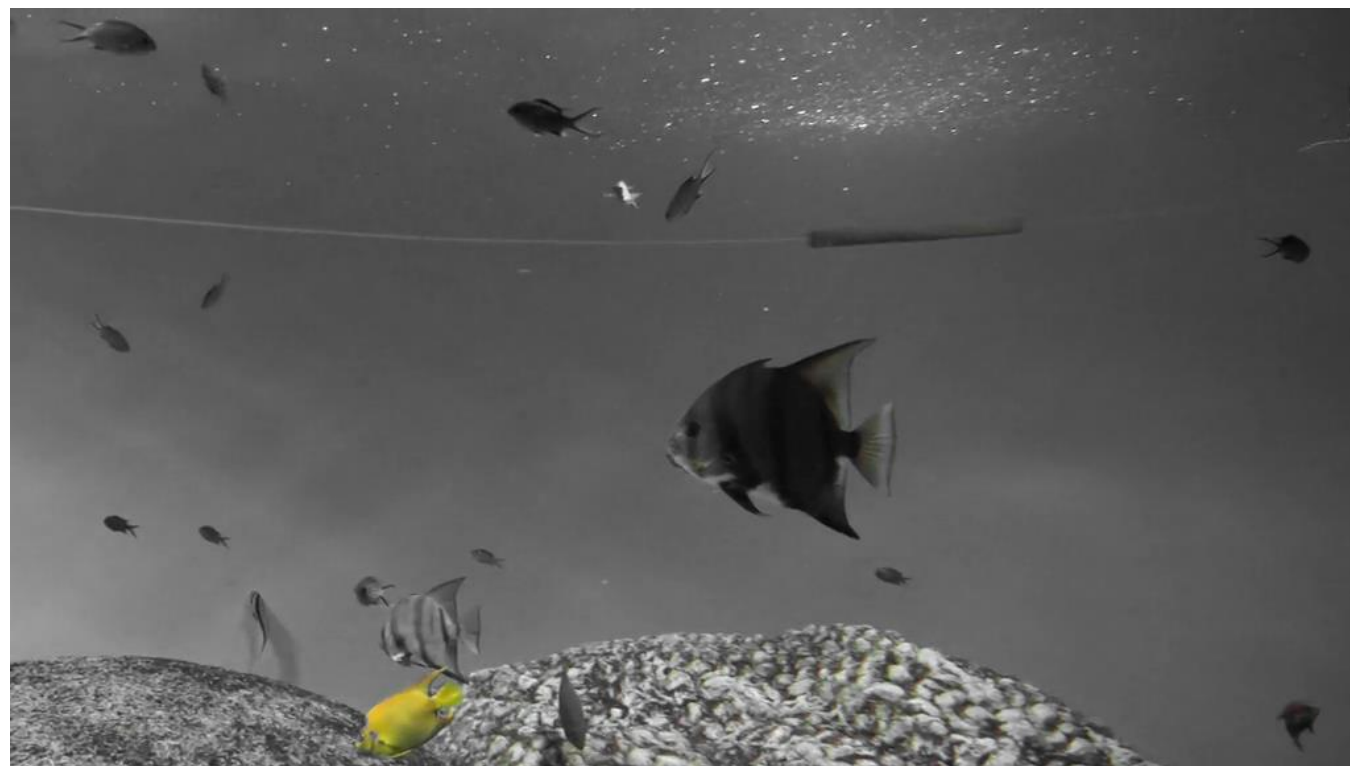
[AQUARIUM AR
THE EXPERIMENT]



[AQUARIUM AR
THE EXPERIMENT]



[AQUARIUM AR
THE EXPERIMENT]



AQUARIUM AR

THE EVALUATION

DATA & TRAINING

- _ Two **species** of fish
- _ **First** species dominated by gray tone



- _ **Second** species dominated by colorful red and yellow tone



- _ **Two** footages, training and evaluation
- _ **600** positive and **250** negative tags for **each** species in **each** footages
- _ **25 stages** of cascade classifier using the LBP feature

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THE EVALUATION

EVALUATION

- The cascade classifier is applied on **each** positive and negative **sample** extracted from the evaluation footage.
- **Test A** is the result of fish detection using proposed processing pipeline on gray colored fish without falling back.
- **Test B** is the standard implementation with only 15 stages of the cascade classifier training which requires the similar amount of time required for training the proposed implementation.

	Proposed	Standard	A	B
True Positive	443	388	393	580
False Negative	157	212	207	20
False Positive	0	0	83	169
True Negative	250	250	167	81
Training Time (second)	227	472	23	17

Higher accuracy



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Lower Training Time

(Hence, faster detection speed)



Proposed Pipeline

(No falling back)

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False Positive	0	0	83	169
True Negative	250	250	167	81
Training Time (second)	227	472	23	17

High False Positive

(Hence, low reliability)

Standard Implementation

(15 stages of classifier back)

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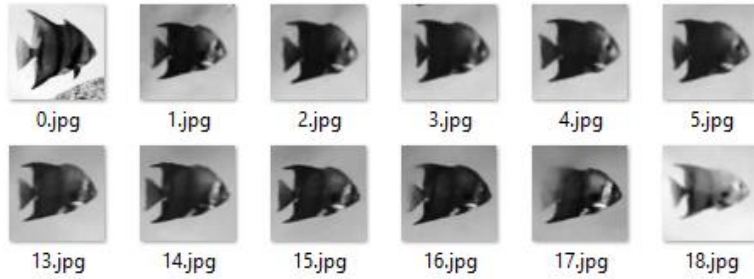
High False Positive

(Hence, low reliability)



Original video feed

TRAINING



Are fishes (Positive)



Are not fishes (Negative)

DETECT



Detect and mark target

AQUARIUM AR CONCLUSION

CONCLUSION

- _ Samples are collected by **manually** tagging process
(Relatively **fast** by using customized software)
- _ Image processing pipeline **enhances** the performance of cascade classifier
(**Fall back** required for gray tone fishes)
- _ **Compelling** detection rate and accuracy

FUTURE WORKS

- _ More efficient mechanism for **orientation invariance**
- _ Fish **tracking** to handle **difficult** poses

{GITS – Waseda University}

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THANK YOU

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